

Is there still room for new developments in geostatistics?

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*Georges Matheron lecture, IAMG
34th IGC, Brisbane, 8 August 2012*



Matheron: books and monographs

- 1962-1963: *Treatise of applied geostatistics* (in French), Technip and BRGM editions, Paris
- 1965: *Regionalized variables and their estimation* (in French), Masson, Paris
- 1967: *Elements for a theory of porous media* (in French), Masson, Paris
- 1968: *Treatise of applied geostatistics* (in Russian), MIR, Moscow
- 1969: *Theory of random sets* (in French), Ecole des Mines de Paris
- 1969: *Geostatistics course* (in French), Mines Paris
- 1969: *Universal kriging* (in French), Mines Paris
- 1970: *Mathematical morphology* (in French), Mines Paris
- 1970: *The theory of regionalized variables and its applications*, Mines Paris
- 1972-1975: *Random sets and integral geometry*, Wiley, New York
- 1978-1989: *Estimating and choosing*, Springer, Berlin

Three recent developments

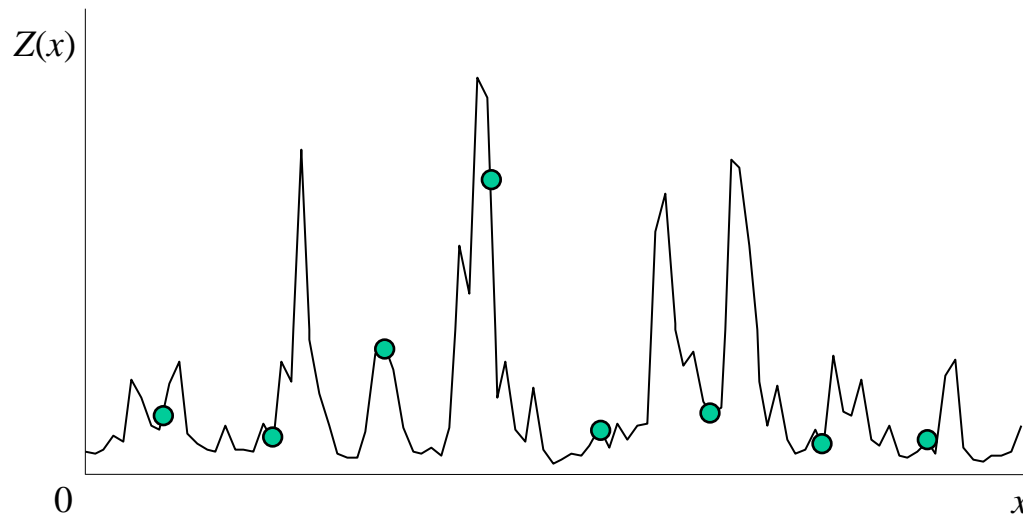
- Dealing with outliers
- Modeling a change of support with the discrete Gaussian model
- Simulating a Gaussian random vector

Dealing with outliers

J. Rivoirard, X. Freulon, et al.

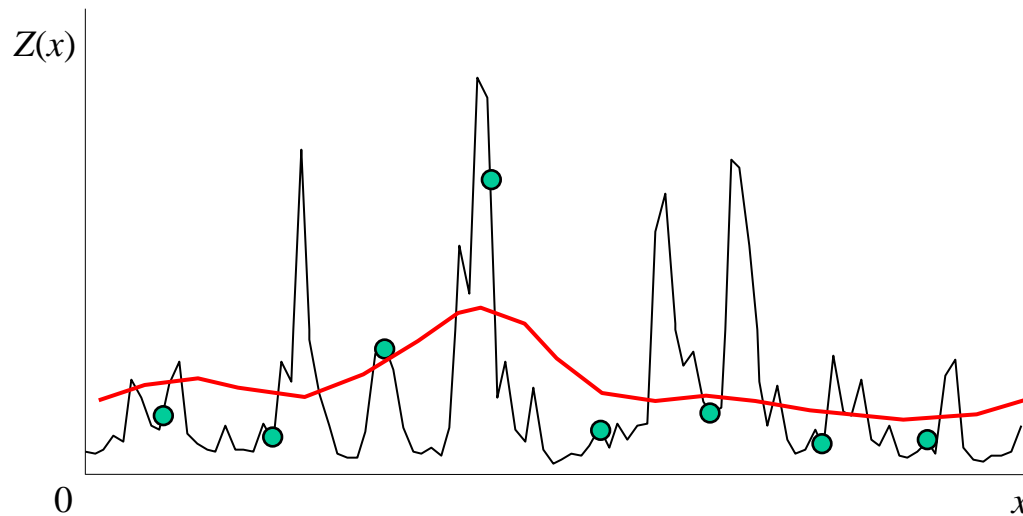
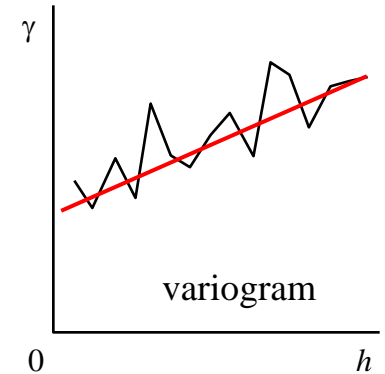
Kriging in the presence of outliers

- Some variables (gold grade, concentration in a pollutant) have a histogram with a long tail. The data include some high values or outliers.
- How can we interpolate?



Standard approach

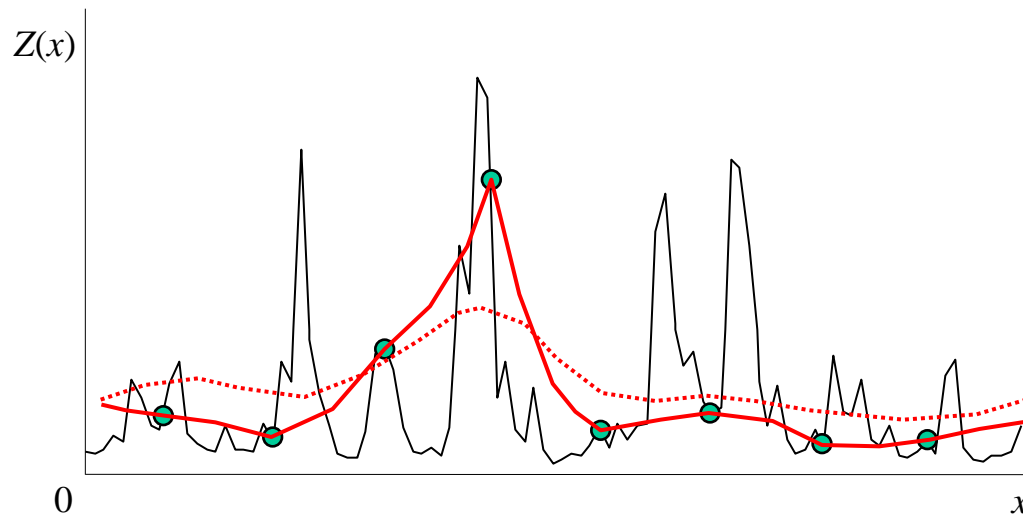
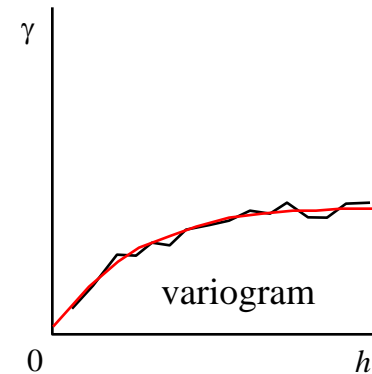
- Lack of robustness of the sample variogram
- Large nugget effect
- Large kriging variance



Ignoring the outlier in the variogram calculation

Kriging with all data

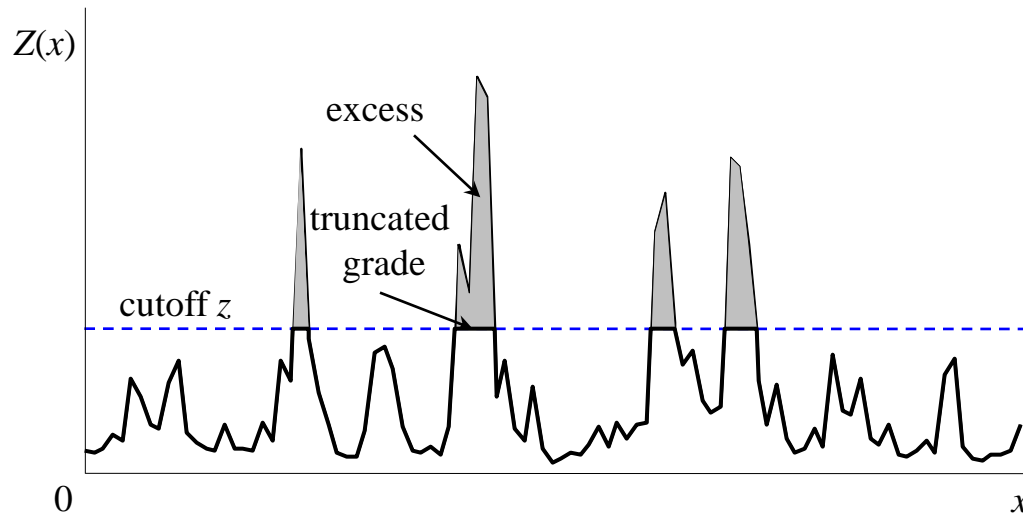
- Robust, but biased, variogram
- Inconsistency between variogram and kriging
- Extends the influence of the outlier data on the basis of the structure of the low grades



Introduction of a cutoff

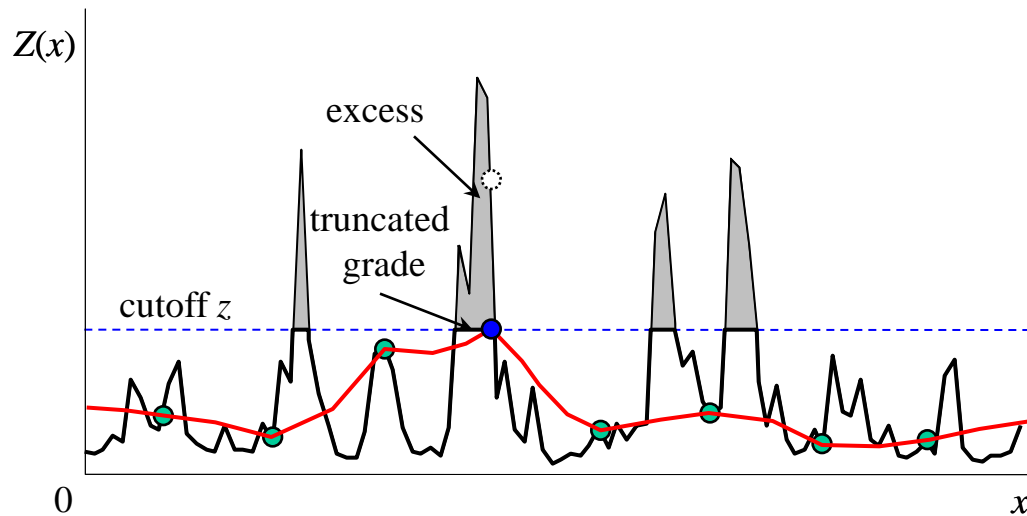
A cutoff z separates $Z(x)$ into

- Truncated grade $\min(Z(x), z)$
- Excess



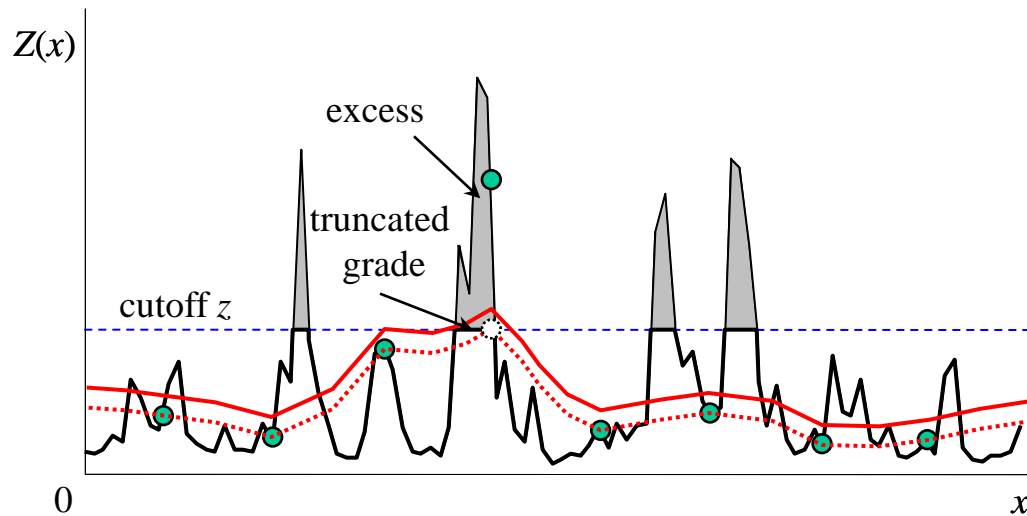
Truncation of large values

- Application of the standard approach to the truncated grade
- More interpretable variogram
- Annihilates the excess



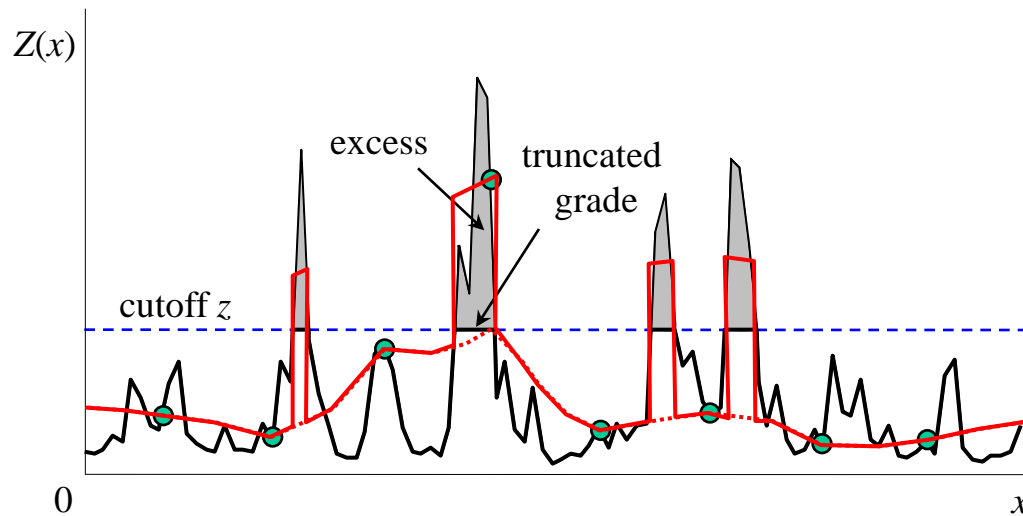
Global spreading of the excess

- Excess considered as a nugget effect and spread over the whole domain
- Consistent globally
- Spreads the excess even in areas where there is no excess



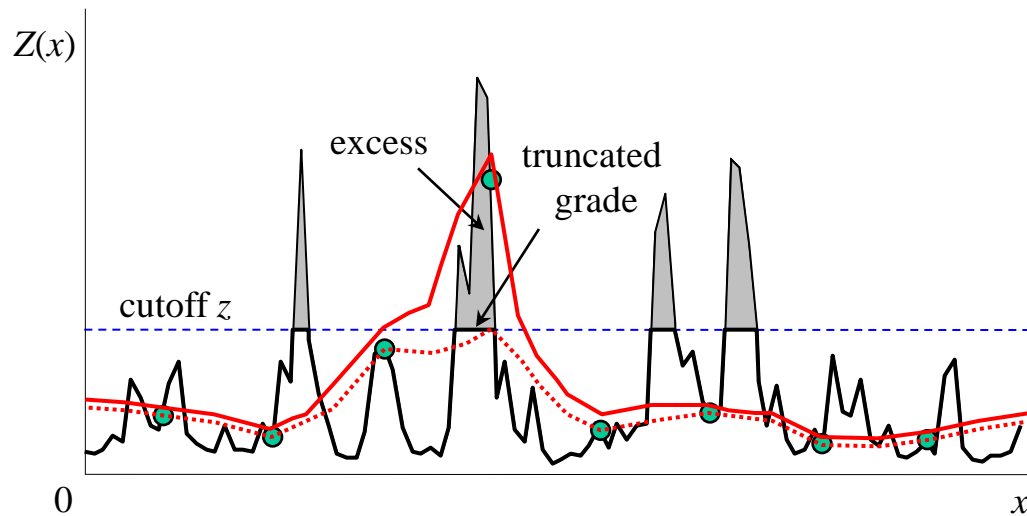
Spreading the excess where there is excess

- OK but requires knowing where there is excess



Spreading the excess where excess is likely

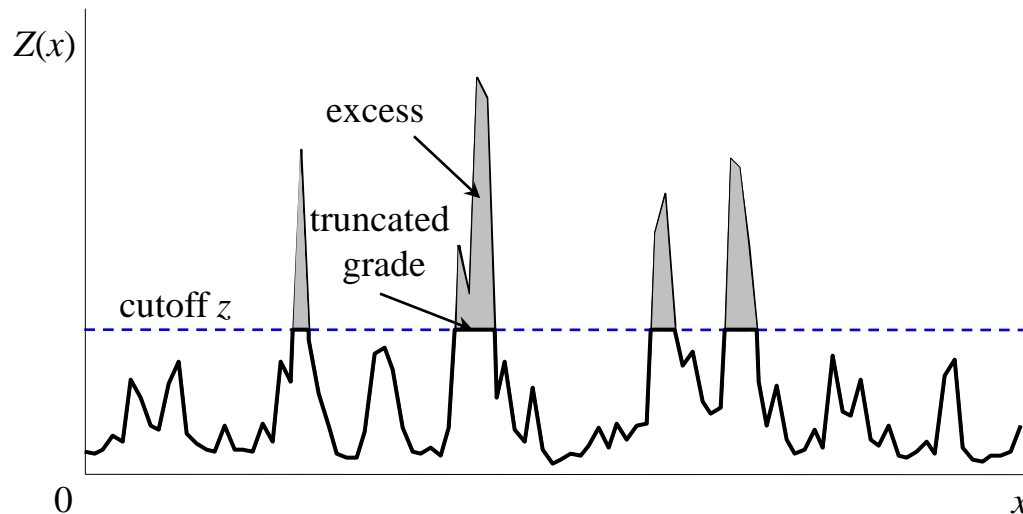
- Estimate the indicator of excess
- Spread the excess proportionally to the indicator estimate



Validity of the approach

$$Z(x) = T(x) + m_E I(x) + R(x)$$

- $T(x) = \min(Z(x), z)$ (truncated grade)
- $I(x) = 1_{Z(x) > z}$ (indicator of the excess)
- $R(x)$: zero-mean residual
- m_E : conditional mean of the excess



Validity of the approach

The model

$$Z(x) = T(x) + m_E I(x) + R(x)$$

is specially interesting when:

- R is spatially uncorrelated with T and I
(no edge effect in the high-value zone)
- R is not structured

Indeed the final estimator is then

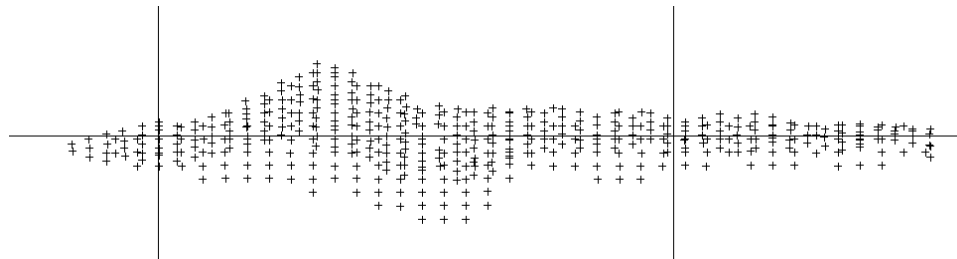
$$Z^*(x) = T^*(x) + m_E I^*(x)$$

(T^* and I^* obtained by cokriging)

It is free from high grades.

Application

- Gold deposit (vertical vein)
- Very skew distribution:
mean = 1.76 g/t, $\sigma/m = 7.74$, maximum = 443 g/t

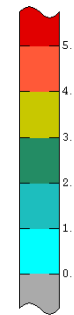
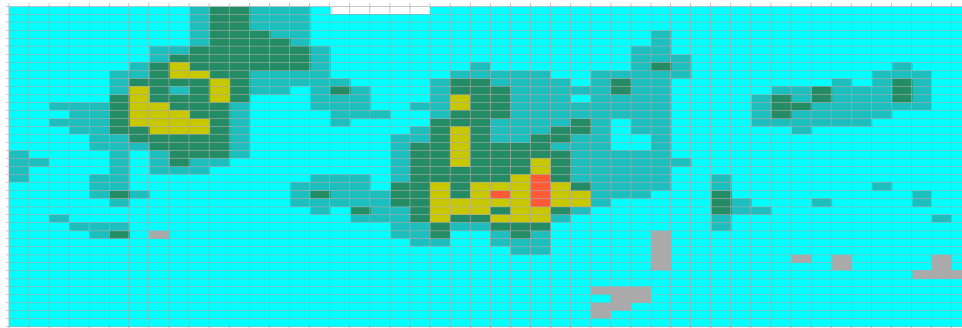


*Top view of the deposit:
Trace of the cross-section and location of the blast holes*

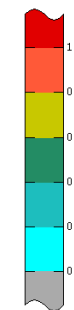
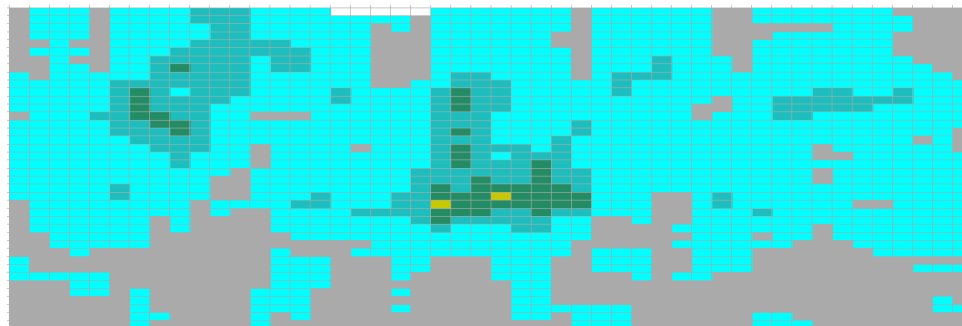
Application

- Cokriging of indicator of excess and truncated grade (cutoff: 5 g/t)

Truncated
grade



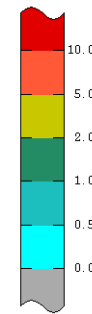
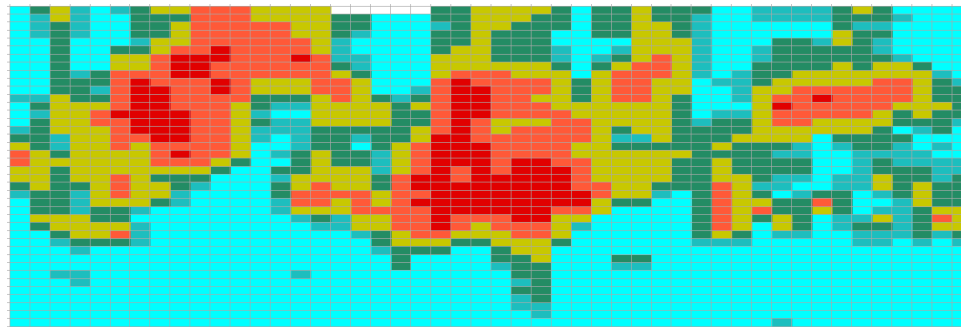
Indicator
of excess



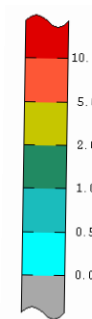
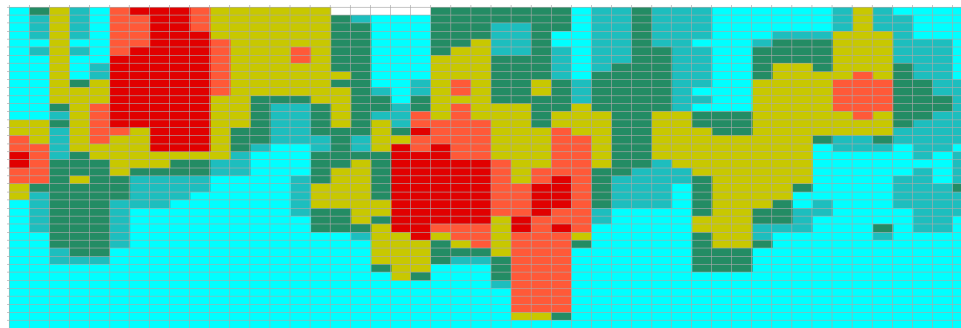
Application

- Final cokriging estimates compared with direct kriging

Final
cokriging
estimates

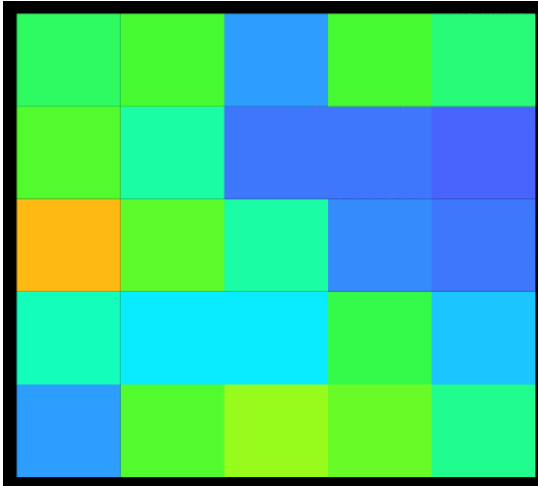


Direct
kriging
estimates

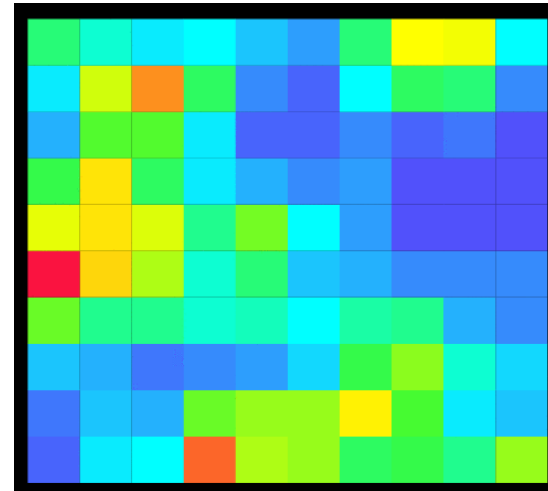


Predicting a change of support with the discrete Gaussian model

Support and selectivity



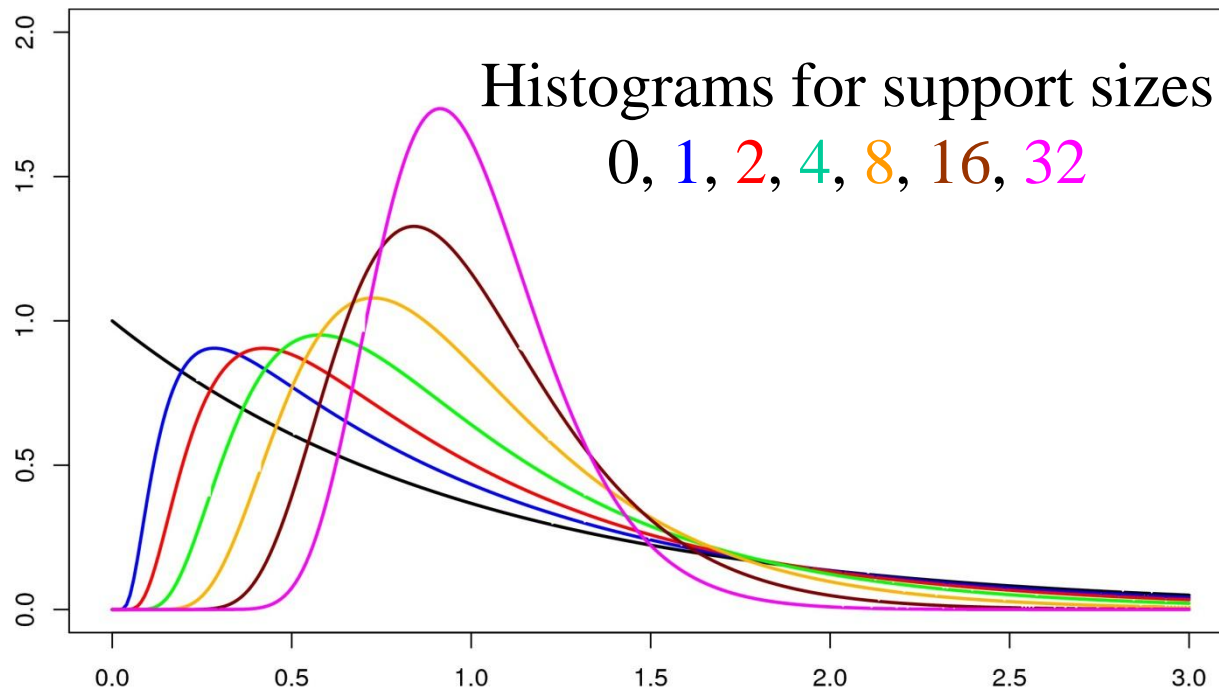
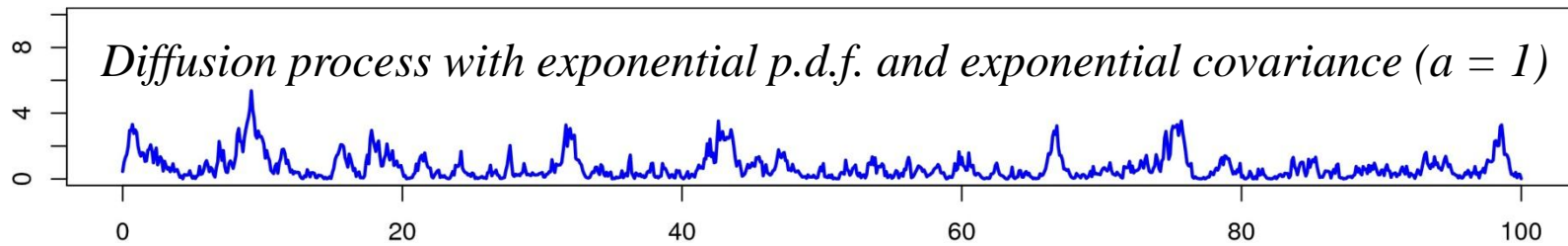
low-contrast variations



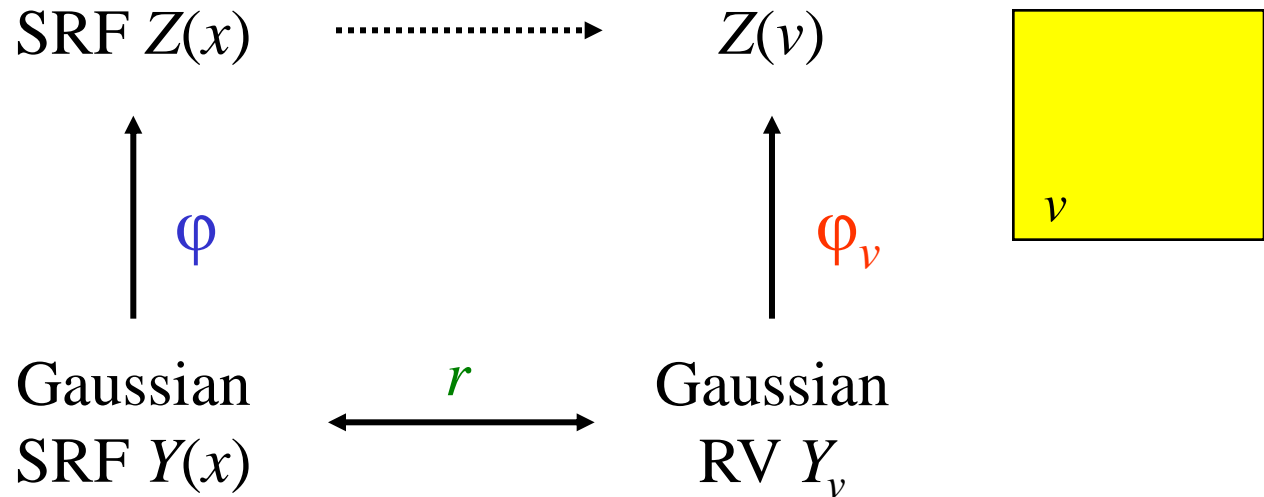
high-contrast variations

Selectivity depends on block size

Support and grade distribution



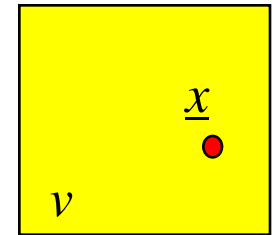
Principle of the discrete Gaussian model



Assumptions of the discrete Gaussian model

Model DGM1 (Matheron, 1976)

Assumption: The pair $(Y(\underline{x}), Y_\nu)$ is bi-Gaussian
(\underline{x} : random point in ν)



Characterized by the correlation coefficient r of $Y(\underline{x})$ and Y_ν

Model DGM2 (Emery, 2007)

Additional assumption: The pair $(Y(\underline{x}), Y(\underline{x}'))$ is bi-Gaussian
($\underline{x}, \underline{x}'$: independently random in ν)

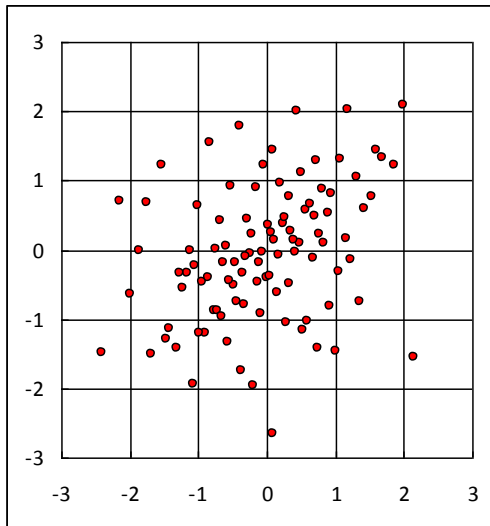
Offers the facility that $Y_\nu = Y(\nu) / r$, where r is the correlation coefficient of $Y(\underline{x})$ and $Y(\nu)$

These assumptions are approximations

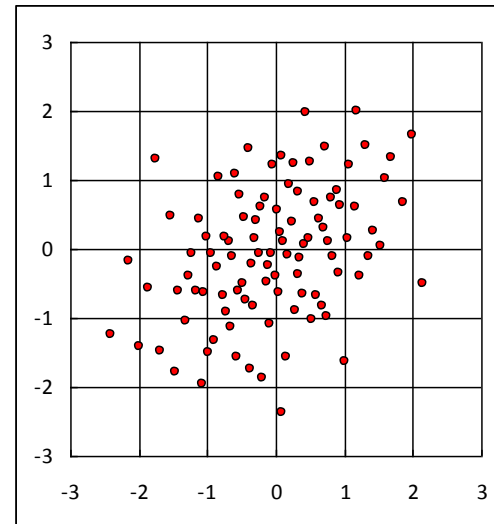
Check of the additional assumption of DGM2

(1D, triangle covariance, segment length = range)

Sample of the true
 $(Y(\underline{x}), Y(\underline{x}'))$ distribution



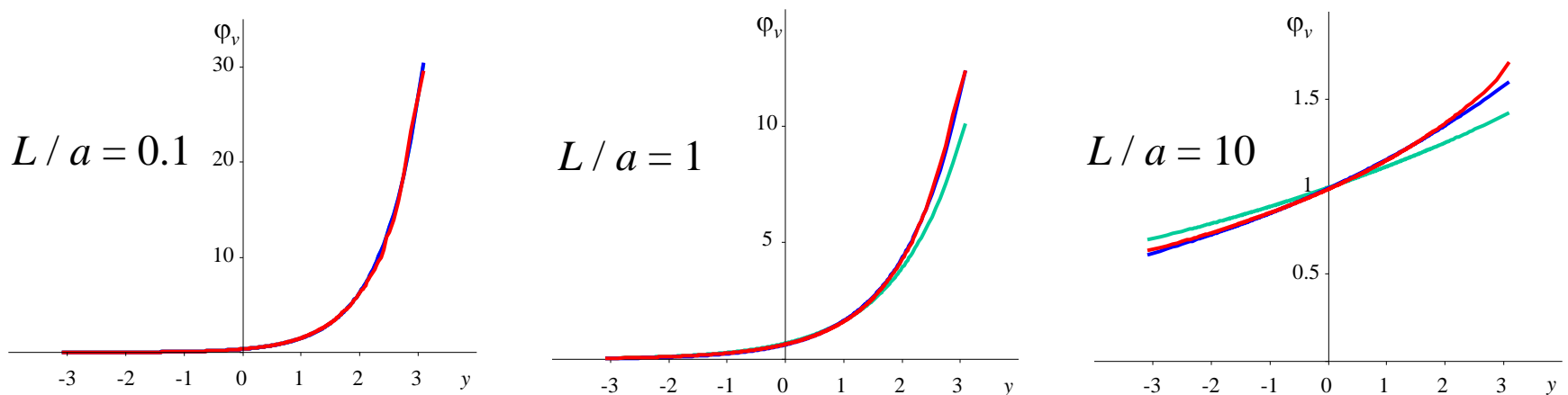
Sample of the approximate
 $(Y(\underline{x}), Y(\underline{x}'))$ distribution



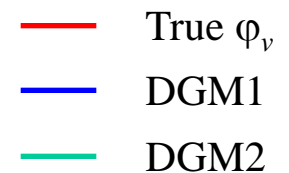
Some dissimilarity

Validity of DGM models: Case of a lognormal SRF

- DGM model = permanence of lognormality
- Example of a logarithmic standard deviation $\sigma = 1.5$
- 2D, square $L \times L$, range a



Comparison of "true" ϕ_v with ϕ_v given by DGM1 and DGM2



Conclusions

DGM1 is more robust than DGM2:

- DGM1 gives a good answer up to a large logarithmic variance.
- DGM2 can be used safely for a small logarithmic variance, and otherwise for a block of small size with respect to the range.

DGM2 facilitates calculations in case of:

- multiple supports
- polymetallic deposit
- information effect

Simulating a Gaussian random vector

C. Lantuéjoul and N. Desassis

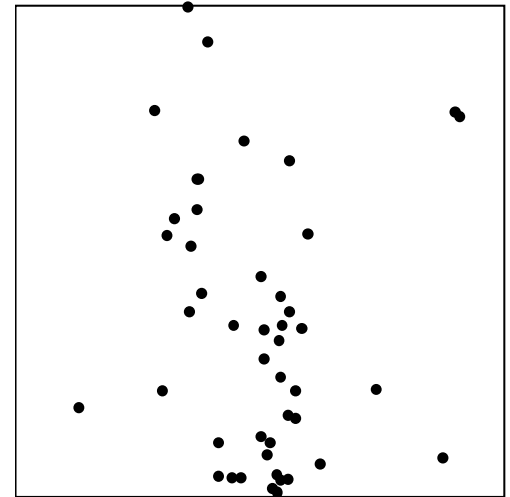
Initial motivation

- Secondary diamond deposits
- Simulation of the number of diamonds in blocks
- Data measured in blocks with various supports



Cox process

- Poisson point process with random intensity (or potential) $Z(x)$
- $Z(x)$ = transform of a Gaussian SRF $Y(x)$
- $Z(v_1), Z(v_2), \dots$ obtained through DGM2
- Conditional simulation: requires the simulation of a large-size Gaussian vector



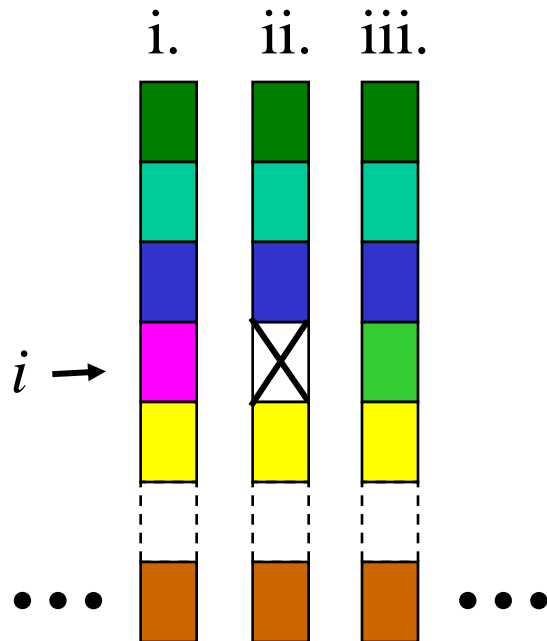
Simulating a large-size Gaussian vector with a given covariance matrix

- Objective:
Simulate a Gaussian vector $\mathbf{Z} = (Z_1, Z_2, \dots, Z_N)$
with zero-mean unit-variance components and
correlation matrix $\boldsymbol{\rho} = [\rho_{ij}]$

Direct approach: Cholesky decomposition

- Well-known solution:
 - Decompose $\boldsymbol{\rho}$ into the product $\mathbf{A} \mathbf{A}'$ where \mathbf{A} is a lower triangular matrix
 - Select a Gaussian vector \mathbf{U} with independent standard normal components
 - Take $\mathbf{Z} = \mathbf{A} \mathbf{U}$
- Limited to a reasonable N

Iterative approach: Gibbs sampler



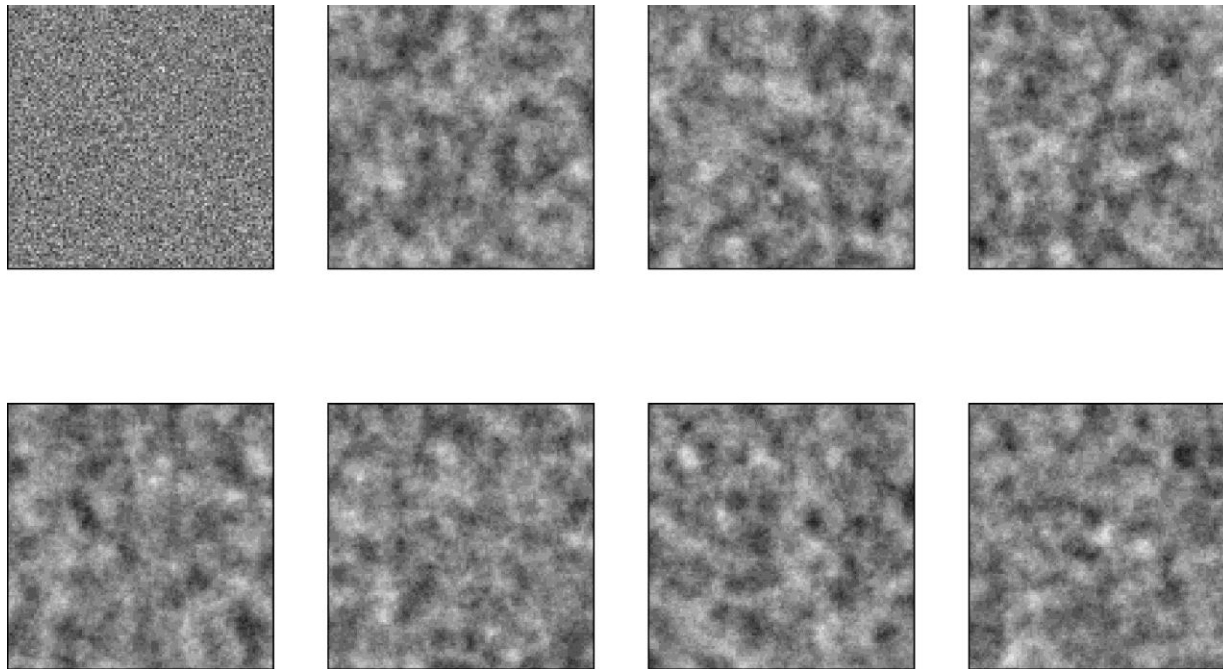
After initialization of vector \mathbf{z} (e.g., $\mathbf{z} = \mathbf{0}$):

- i. Select a component, say i
- ii. Delete the value of this component
- iii. Choose a new value from the conditional distribution of Z_i given the other components
- iv. Go to i.

- The parameters of the conditional distributions derive from the inverse ρ^{-1}
- Can diverge if one uses the conditional distribution from a subset of the data (moving neighborhood)

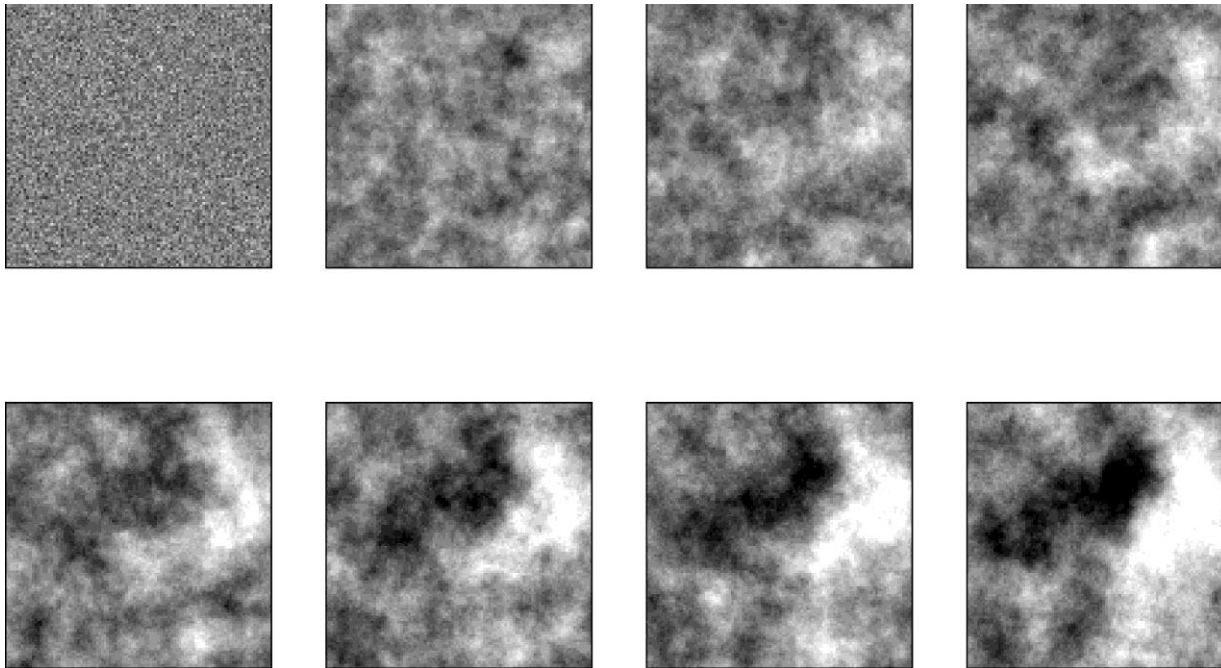
Iterative approach: Gibbs sampler

Grid 100×100 , spherical variogram with range 10, neighborhood 15×15



Iterative approach: Gibbs sampler

Grid 100×100 , spherical variogram with range 10, neighborhood 5×5



Reversing the viewpoint

- Two useful properties:
 - ✓ If $\boldsymbol{\rho}$ is a covariance matrix, its inverse $\boldsymbol{\rho}^{-1}$ is a covariance matrix.
 - ✓ If the vector \mathbf{Y} has mean $\mathbf{0}$ and covariance $\boldsymbol{\rho}^{-1}$, $\mathbf{Z} = \boldsymbol{\rho} \mathbf{Y}$ has mean $\mathbf{0}$ and covariance $\boldsymbol{\rho}$.
- A solution:
 - ✓ Use the Gibbs sampler to simulate \mathbf{Y} ; then, derive \mathbf{Z} .
- Requires the inverse $(\boldsymbol{\rho}^{-1})^{-1}$, which is known (it is nothing but $\boldsymbol{\rho}$)

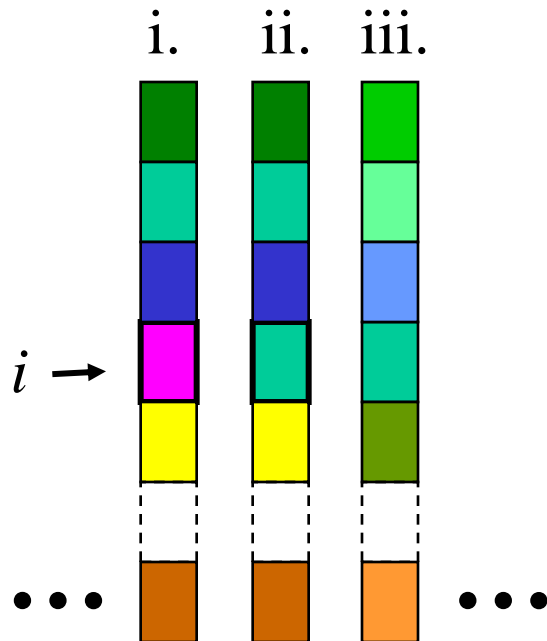
Suppressing the reference to \mathbf{Y}

- Suppose that \mathbf{Z} has mean $\mathbf{0}$ and correlation matrix ρ .
- If the component Z_i is changed into Z_i' , possibly correlated with Z_i but conditionally independent of the other Z_j 's, let us consider

$$Z_j' = Z_j + \rho_{ji} (Z_i' - Z_i) \quad j \neq i$$

- It can be shown that \mathbf{Z}' also has covariance matrix ρ .

Propagation algorithm



After initialization of vector \mathbf{z} (e.g., $\mathbf{z} = \mathbf{0}$):

- i. Select a component, say i
- ii. Choose a new value for this component
- iii. Propagate its influence on the other components
- iv. Go to i.

- Different strategies for the choice of the new value
- Does not require the inverse ρ^{-1}

Propagation algorithm

- Achieves what seemed impossible:
 Simulate without inverting the covariance matrix
- Can therefore be used to simulate very large vectors

Conclusion

- It is worth revisiting standing problems
- What seems impossible may become straightforward once a sound solution has been found
- Is there still room for new developments in geostatistics?
 - Yes!
 - and even in classical geostatistics!



Special acknowledgements to
Georges Matheron (1930–2000)
who continues to be a source of inspiration



*Georges Matheron lecture, IAMG
34th IGC, Brisbane, 8 August 2012*

